

- Accepts +/- 0.010" Axial Shaft Play
- 50 to 5,000 Cycles per Revolution (CPR)
- Tracks 0 to 300,000 Cycles per Second
- 2-Channel Quadrature Differential Squarewave Outputs
- Third Index Channel
- Operating Temperature of $-40^{\circ}$ to $+100^{\circ} \mathrm{C}$
- Powered from a Single +5VDC Power Supply

- RoHS Compliant and REACH Certified

The ENC-A5DI is a differential encoder designed for quick and simple assembly to any minimum shaft length 0.445 " and maximum shaft length of .570 ", and shaft size ranging from 0.079 " to 0.394 " in diameter. The ENC-A5DI module is designed to detect the rotary position with a code wheel. When attached to the end of a shaft, the encoder provides digital feedback information. This differential encoder consists of a LED source lens and a monolithic detector IC enclosed in a small polymer package. These modules implement phased array detector technology providing superior performance and tolerances over traditional aperture mask type encoders. The ENCA5DI series provides digital quadrature differential outputs on all resolutions and are capable of sinking or sourcing 8 mA each. These encoders are powered from a single +5VDC power supply and are RoHS compliant and REACH certified.


L010727

## DEFAULT OPTION:



E-Option:


H-Option:


Default Option:


Note: Dimensions are in inches

| Cover Options: | Description |
| :---: | :---: |
| E- Option | E-Option provides a cylindrical extension cover for larger shafts. The required shaft length is $.445^{\prime \prime}$ to $.750^{\prime \prime}$. <br> Note: E-option + R-Option the required shaft length is .570 " to .875". |
| H- Option | Shafts 2 mm to $1 / 4^{\prime \prime}$, a $.295^{\prime \prime}$ diameter hole is supplied. <br> Shafts $5 / 16^{\prime \prime}$ to 10 mm , a $.438^{\prime \prime}$ diameter hole is supplied. <br> Required shaft length $>0.445^{\prime \prime}$ <br> Note: H-Option + R-Option the required shaft length is > .570" |
| Default Option | The required length is $.445^{\prime \prime}$ to $.570^{\prime \prime}$ <br> Note: Default Option + R-Option the required shaft length is . $570^{\prime \prime}$ to $.695^{\prime \prime}$ |

## 3-OPTION:



3-Option: Makes all five hole diameters $.125^{\prime \prime}$
(Note: Base Mounting Screws are NOT included. \#2-56 or \#4-40 screws can be used to mount the base to your mounting surface.)


Differential Encoder Timing Diagram

A-Option: Adds a .497" diameter alignment shoulder designed to slip into a $.500^{\prime \prime}$ diameter recess in the mounting surface centered around the shaft.

R-Option: Adapter is an $1 / 8^{\prime \prime}$ thick fiberglass adapter which is pre-mounted to the base of the encoder. It allows the encoder to rotate +/- 15 degrees.
"This option adds $1 / 8$ " to the required shaft length.



G-Option: Includes molded ears which enables it to be mounted to a $1.812^{\prime \prime}$ diameter bolt circle. Mounting holes are designed to fit $4-40$ screws. Will work with shaft lengths of $.445^{\prime \prime}$ to $.570^{\prime \prime}$ and does not add to the required shaft length.

DIFFERENTIAL ENCODER PINOUT TOP OF ENCODER FACING PLUG



| Model \# | Description |  |  |  |  |  |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| CPR(N): | The Number of Cycles Per Revolution |  |  |  |  |  |
| One Shaft Rotation: | 360 mechanical degrees, N cycles |  |  |  |  |  |
| One Electrical Degree ( ${ }^{\circ} \mathrm{e}$ ): | 1/360th of one cycle |  |  |  |  |  |
| One Cycle (C): | 360 electrical degrees $\left({ }^{\circ} \mathrm{e}\right)$. Each cycle can be decoded into 1 or 4 codes, referred to as X 1 or X 4 resolution multiplication |  |  |  |  |  |
| Symmetry: | A measure of the relationship between ( X ) and $(\mathrm{Y})$ in electrical degrees, nominally 180 ${ }^{\circ} \mathrm{e}$ |  |  |  |  |  |
| Quadrature (Z): | The phase lag or lead between channels A and $B$ in electrical degrees, nominally $90^{\circ} \mathrm{e}$ |  |  |  |  |  |
| Index (CH I): | The Index Output goes high once per revolution, coincident with the low states of channels $A$ and $B$, nominally $1 / 4$ of one cycle ( $90^{\circ} \mathrm{e}$ ) |  |  |  |  |  |
| Timing Characteristics |  | Symbol | Min | Typ | Max | Units |
| Cycle Error |  | C | - | 3.0 | 5.5 | ${ }^{\circ} \mathrm{e}$ |
| Symmetry |  | X, Y | 150 | 180 | 210 | ${ }^{\circ} \mathrm{e}$ |
| Quadrature |  | Z | 60 | 90 | 120 | ${ }^{\circ} \mathrm{e}$ |
| Index Pulse Width |  | Po | 60 | 90 | 120 | ${ }^{\circ} \mathrm{e}$ |
| Ch. I Rise After Ch. B or Ch. A | A Fall | t1 | 10 | 100 | 250 | ns |
| Ch. I Fall After Ch. B or Ch. A | Rise | t2 | 70 | 150 | 300 | ns |


| Parameter | Min | Typ | Max | Units |
| :---: | :---: | :---: | :---: | :---: |
| Supply Voltage | 4.5 | 5.0 | 5.5 | Volts |
| Supply Current <br> CPR < 500, no load <br> $C P R \geq 500$ and $<2000$, no load <br> CPR $\geq 2000$ |  | $\begin{aligned} & 29 \\ & 57 \\ & 73 \end{aligned}$ | $\begin{aligned} & 36 \\ & 65 \\ & 88 \end{aligned}$ | mA |
| Output Low ( $\mathrm{I}_{\mathrm{OL}}=8 \mathrm{~mA}$ max) | - | 0.2 | 0.4 | Volts |
| Output High* $\mathrm{I}_{\mathrm{OL}}=-8 \mathrm{~mA} \max$ | 2.4 | 3.4 | - | Volts |
| Differential Output Rise/ Fall Time | - | - | 15 | nS |

* Unloaded high level output voltage is 4.80 V typically, 4.2 V minimum.

| Recommended Operating <br> Conditions | Min | Max |
| :--- | :---: | :---: |
| Units |  |  |
| Temperature (CPR <2000) | -40 | 100 |
| ${ }^{\circ} \mathrm{C}$ |  |  |
| Temperature (CPR $\geq 2000$ ) | -25 | 100 |
| ${ }^{\circ} \mathrm{C}$ |  |  |
| Load Capacitance | - | 100 |
| Count Frequency <br> (CPR $\leq 1250)$ | - | 300 |
| Count Frequency <br> (CPR 2000-2500) | - | 360 |
| Count Frequency (CPR <br> $4000+$ ) | - | 720 |


| Parameter | Max | Units |
| :---: | :---: | :---: |
| Vibration (5 to 2 kHz$)$ | 20 | g |
| Shaft Axial Play | $+/-0.01$ | in. |
| Shaft Eccentricity Plus Radial Play | 0.004 | in. |
| Acceleration | 250,000 | $\mathrm{rad} / \mathrm{sec}^{2}$ |


| Speed Calculation |  | Units |
| :---: | :---: | :---: |
| CPR $<2000$ | $18 \times 10^{6} /$ CPR | RPM |
| CPR $\geq 2000$ and $<4000$ | $21.6 \times 10^{6} /$ CPR | RPM |
| CPR $\geq 4000$ | $43.2 \times 10^{6} /$ CPR | RPM |

*60,000 RPM is the maximum RPM due to mechanical limitations.

## Cables:

The following cables are compatible with Anaheim Automation's A5DI series encoder. Select a cable length from the table below:

| Cable Part Number | Length |
| :---: | :---: |
| ENC-CBL-AA4706 | 1 ft. |
| ENC-CBL-AA4706-5 | 5 ft. |
| ENC-CBL-AA4706-10 | 10 ft. |
| ENC-CBL-AA4706-20 | 20 ft. |

NOTE: For pricing and other information on cables and centering tools, please visit Accessories on our website.

## Centering Tools:

Centering tools are optional, but recommended for a more precise installation.

