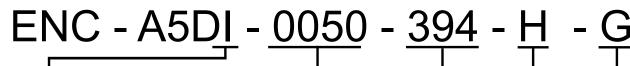




- Accepts +/- 0.010" Axial Shaft Play
- 50 to 5,000 Cycles per Revolution (CPR)
- Tracks 0 to 300,000 Cycles per Second
- 2-Channel Quadrature Differential Squarewave Outputs
- Third Index Channel
- Operating Temperature of -40° to +100° C
- Powered from a Single +5VDC Power Supply
- RoHS Compliant and REACH Certified



The ENC-A5DI is a differential encoder designed for quick and simple assembly to any minimum shaft length 0.445" and maximum shaft length of .570", and shaft size ranging from 0.079" to 0.394" in diameter. The ENC-A5DI module is designed to detect the rotary position with a code wheel. When attached to the end of a shaft, the encoder provides digital feedback information. This differential encoder consists of a LED source lens and a monolithic detector IC enclosed in a small polymer package. These modules implement phased array detector technology providing superior performance and tolerances over traditional aperture mask type encoders. The ENC-A5DI series provides digital quadrature differential outputs on all resolutions and are capable of sinking or sourcing 8 mA each. These encoders are powered from a single +5VDC power supply and are RoHS compliant and REACH certified.



Index		CPR		Bore	Size	Cover Options
I = Index	50	400	1250	079 = 2mm	236 = 6mm	E = Cover Extension
(3rd Channel)	96	500	2000	118 = 3mm	250 = 1/4"	H = Hole in Cover
	100	512	2048	125 = 1/8"	276 = 7mm	Blank = Default
	192	540	2500	156 = 5/32"	313 = 5/16"	
	200	720	4000	157 = 4mm	315 = 8mm	
	250	900	4096	188 = 3/16"	375 = 3/8"	Base Options
	256	1000	5000	197 = 5mm	394 = 10mm	
	360	1024				3 = Base Mounting Holes Becc

A = Adds Self-Aligning Shoulder to Base G = Adds 1.812" Mounting Ears to Base R = Adds 3-Slot Adapter to Bottom of Base Blank = Default

DESCRIPTION

EATURES

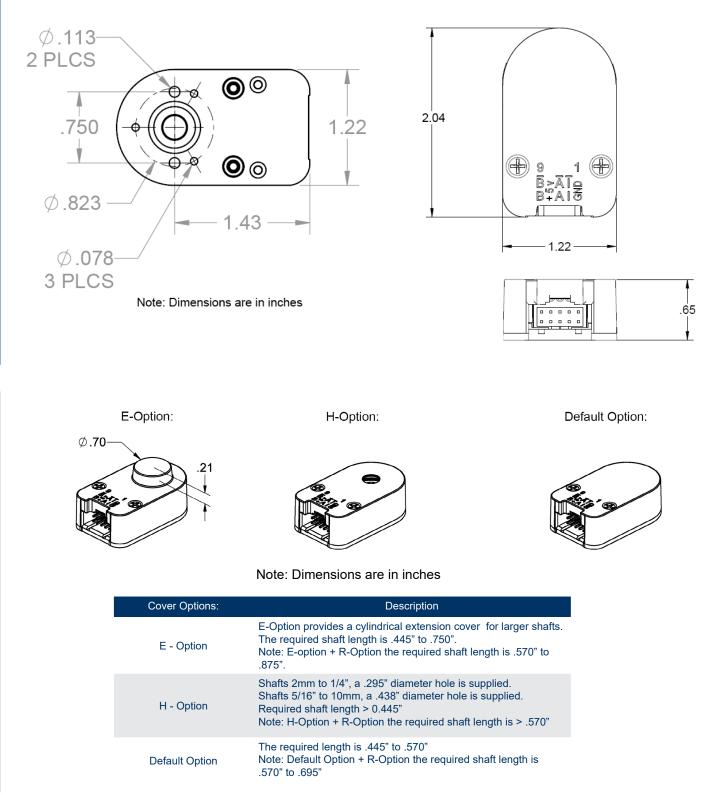
L010727



DIMENSIONS

COVER OPTIONS

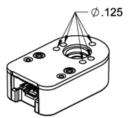
DEFAULT OPTION:



www.anaheimautomation.com

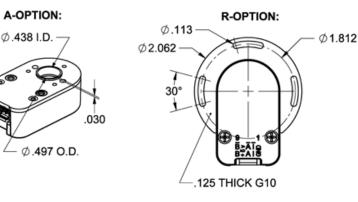


3-OPTION:



3-Option: Makes all five hole diameters .125"

centered around the shaft.



A-Option: Adds a .497" diameter alignment R-Option: Adapter is an 1/8" thick fiberglass shoulder designed to slip into a .500" adapter which is pre-mounted to the base diameter recess in the mounting surface of the encoder. It allows the encoder to rotate +/- 15 degrees.

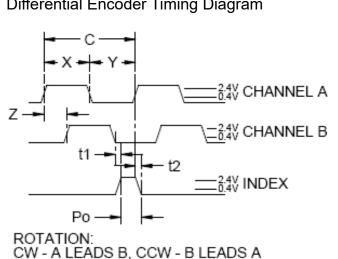
*This option adds 1/8" to the required shaft length.

Note: All dimensions are in inches

Ø.109

2 PLCS

(Note: Base Mounting Screws are NOT included. #2-56 or #4-40 screws can be used to mount the base to your mounting surface.)



DIFFERENTIAL ENCODER PINOUT TOP OF ENCODER FACING PLUG

G-OPTION: 2.11 1.812

G-Option: Includes molded ears which enables it to be mounted to a 1.812" diameter bolt circle. Mounting holes are designed to fit 4-40 screws. Will

work with shaft lengths of .445" to .570" and does

not add to the required shaft length.

-6

.135 THICK

9	7	5	3	1
	•	•	•	• •
	0			nction
Ground			ound	
Ground				
I-Channel				
I+Channel				
A-Channel				
A+Channel				
Power				
Power				
B-Channel				
		В	+C	hannel
	•		10 8 6	10 8 6 4 Fur Gr I-Cr I+Cl A-Cl A+C Pc B-Cl

Differential Encoder Timing Diagram

4985 East Landon Drive Anaheim, CA 92807 Tel. (714) 992-6990 Fax. (714) 992-0471 www.anaheimautomation.com



Model #	Description
CPR(N):	The Number of Cycles Per Revolution
One Shaft Rotation:	360 mechanical degrees, N cycles
One Electrical Degree (°e):	1/360th of one cycle
One Cycle (C):	360 electrical degrees (°e). Each cycle can be decoded into 1 or 4 codes, referred to as X1 or X4 resolution multiplication
Symmetry:	A measure of the relationship between (X) and (Y) in electrical degrees, nominally 180 $^\circ\text{e}$
Quadrature (Z):	The phase lag or lead between channels A and B in electrical degrees, nominally 90 °e
Index (CH I):	The Index Output goes high once per revolution, coincident with the low states of channels A and B, nominally 1/4 of one cycle (90°e)

Timing Characteristics	Symbol	Min	Тур	Max	Units
Cycle Error	С	-	3.0	5.5	°e
Symmetry	X,Y	150	180	210	°e
Quadrature	Z	60	90	120	°e
Index Pulse Width	Po	60	90	120	°e
Ch. I Rise After Ch. B or Ch. A Fall	t1	10	100	250	ns
Ch. I Fall After Ch. B or Ch. A Rise	t2	70	150	300	ns

Parameter	Max	Units
Vibration (5 to 2kHz)	20	g
Shaft Axial Play	+/- 0.01	in.
Shaft Eccentricity Plus Radial Play	0.004	in.
Acceleration	250,000	rad/sec ²

Parameter	Min	Тур	Max	Units
Supply Voltage	4.5	5.0	5.5	Volts
Supply Current CPR < 500, no load CPR \ge 500 and < 2000, no load CPR \ge 2000	- -	29 57 73	36 65 88	mA
Output Low (I _{OL} = 8mA max)	-	0.2	0.4	Volts
Output High* I _{OL} = -8mA max Differential Output Rise/ Fall Time	2.4	3.4	- 15	Volts nS

* Unloaded high level output voltage is 4.80V typically, 4.2V minimum.

Recommended Operating Conditions	Min	Max	Units
Temperature (CPR < 2000)	-40	100	°C
Temperature (CPR ≥ 2000)	-25	100	°C
Load Capacitance	-	100	pF
Count Frequency (CPR ≤ 1250)	-	300	kHz
Count Frequency (CPR 2000-2500)	-	360	kHz
Count Frequency (CPR 4000+)	-	720	kHz

Speed Cal	Units	
CPR < 2000	18x10 ⁶ / CPR	RPM
CPR ≥ 2000 and < 4000	21.6x10 ⁶ / CPR	RPM
CPR ≥ 4000	43.2x10 ⁶ / CPR	RPM

*60,000 RPM is the maximum RPM due to mechanical limitations.

Cables:

The following cables are compatible with Anaheim Automation's A5DI series encoder. Select a cable length from the table below:

Cable Part Number	Length
ENC-CBL-AA4706	1 ft.
ENC-CBL-AA4706-5	5 ft.
ENC-CBL-AA4706-10	10 ft.
ENC-CBL-AA4706-20	20 ft.

NOTE: For pricing and other information on cables and centering tools, please visit Accessories on our website.

Centering Tools:

Centering tools are optional, but recommended for a more precise installation.

ENC-C	ΤΟΟΙ	250

Bore Size			
079=2mm	236=6mm		
118=3mm	250=1/4"		
125=1/8"	276=7mm		
157=4mm	313=5/15"		
188=3/16"	375=3/8"		
197=5mm	394=10mm		